

# Quantum gravity from the point of view of locally covariant QFT

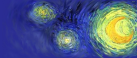
Katarzyna Rejzner<sup>1</sup>

INdAM (Marie Curie) fellow  
University of Rome Tor Vergata

Wuppertal, 01.06.2013

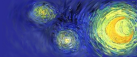
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<sup>1</sup>Based on the joint work with Klaus Fredenhagen and Romeo Brunetti



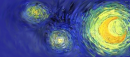
# Outline of the talk

- 1 Introduction
  - Effective quantum gravity
  - Local covariance
- 2 Classical theory
  - Kinematical structure
  - Equations of motion and symmetries
  - BV complex
- 3 Quantization
  - Deformation quantization
  - Background independence



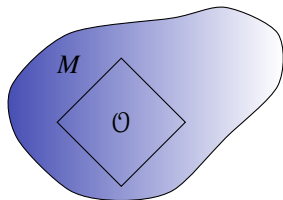
## Intuitive idea

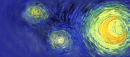
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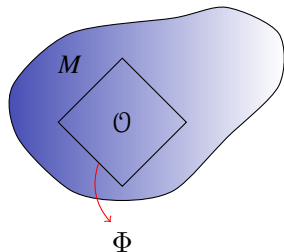
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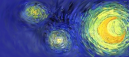




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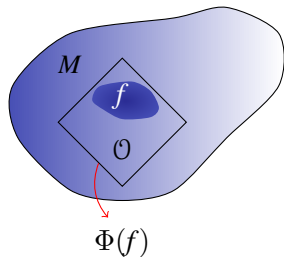
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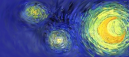




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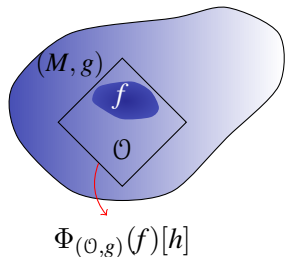
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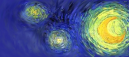


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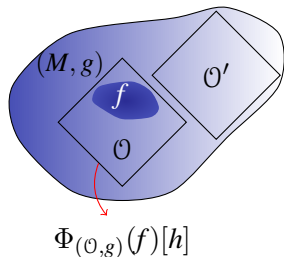


$$\Phi_{(\mathcal{O},g)}(f)[h]$$

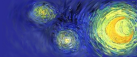


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- Diffeomorphism transformation: move our experimental setup to a different region  $\mathcal{O}'$ .

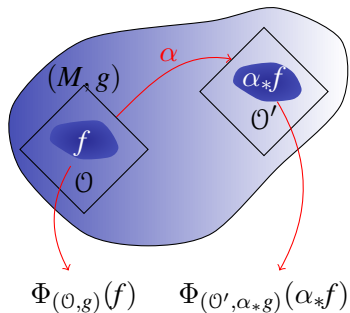


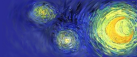




## How to implement it?

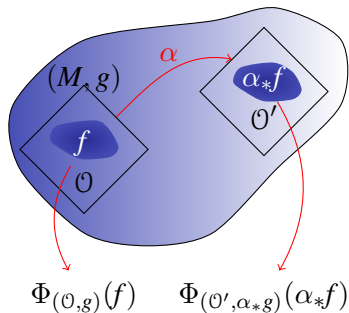
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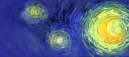




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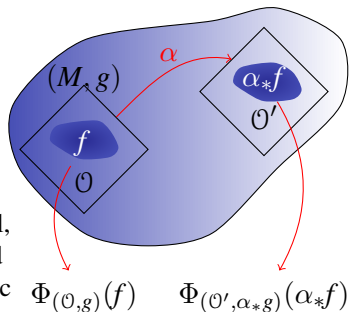
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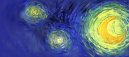




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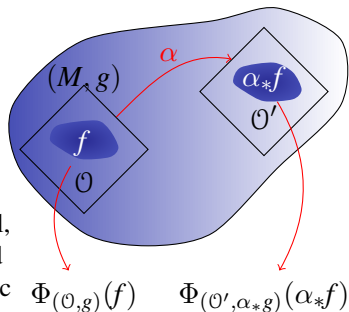
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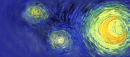




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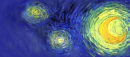
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  - **Vec** with (small) topological vector spaces as **objects** and injective continuous homomorphisms of topological vector spaces as **morphisms**.





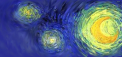
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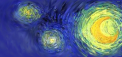
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- We define a contravariant functor  $\mathfrak{E} : \mathbf{Loc} \rightarrow \mathbf{Vec}$ , which assigns to a spacetime the corresponding configuration space and acts on morphisms  $\chi : \mathcal{M} \rightarrow \mathcal{N}$  as  $\mathfrak{E}\chi = \chi^* : \mathfrak{E}(\mathcal{N}) \rightarrow \mathfrak{E}(\mathcal{M})$ .

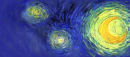


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- In a similar way we define a covariant functor  $\mathfrak{E}_c : \mathbf{Loc} \rightarrow \mathbf{Vec}$  by setting  $\mathfrak{E}_c\chi = \chi_*$ , where:

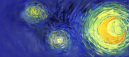
$$\chi_*h \doteq \begin{cases} (\chi^{-1})^*h(x) & , \quad x \in \chi(M), \\ 0 & , \quad \text{else} \end{cases}$$





## Functionals and dynamics

- We consider the space of smooth functionals on  $\mathfrak{E}(\mathcal{M})$ , i.e.  $\mathcal{C}^\infty(\mathfrak{E}(\mathcal{M}), \mathbb{R})$ .

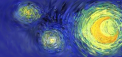


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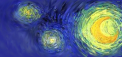
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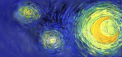
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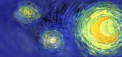
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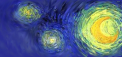
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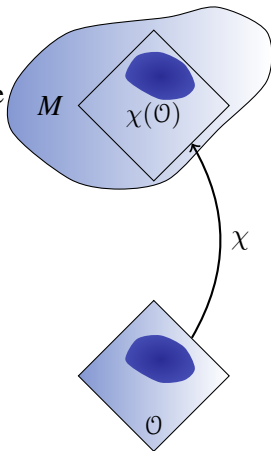
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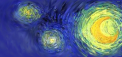
$$S_{(M,g)}(f)[h] \doteq \int R[\tilde{g}]f \, d \text{vol}_{(M,\tilde{g})}, \quad \tilde{g} = g + h.$$



## Fields as natural transformations

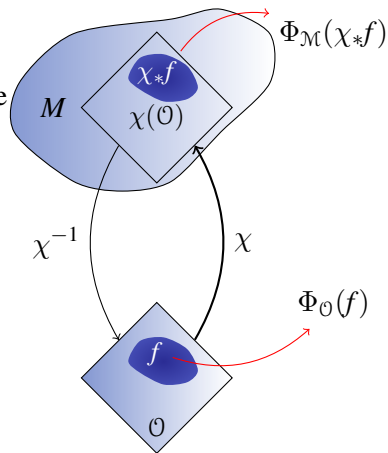
- In the framework of locally covariant field theory [Brunetti-Fredenhagen-Verch 2003], fields are natural transformation between certain functors. Let  $\Phi \in \text{Nat}(\mathcal{D}, \mathfrak{F})$ , where  $\mathcal{D}$  is the functor of test function spaces  $\mathcal{D}(\mathcal{M}) = \mathcal{C}_c^\infty(M)$  (one could substitute  $\mathfrak{F}$  with a functor to the category of Poisson or  $C^*$ -algebras).



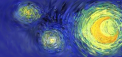


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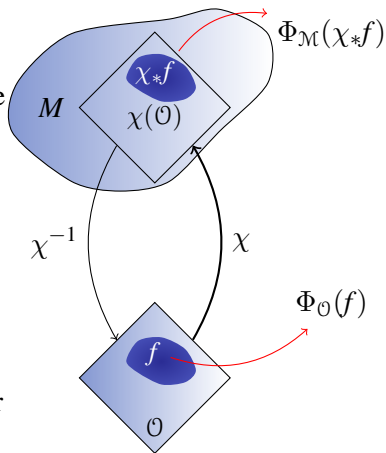


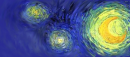




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- $\Phi$  is a natural transformation if  $\Phi_{\mathcal{O}}(f)[\chi^*h] = \Phi_{\mathcal{M}}(\chi_*f)[h]$  holds.
- In classical gravity we understand physical quantities not as pointwise objects but rather as something defined **on all the spacetimes in a coherent way**.

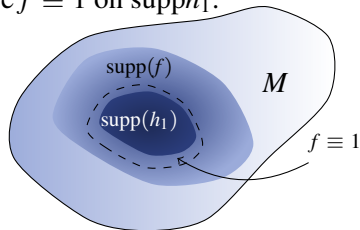


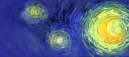


# Equations of motion and symmetries

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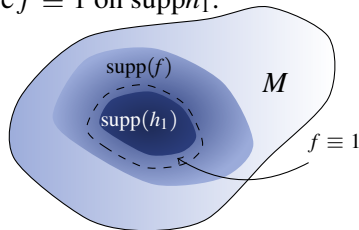
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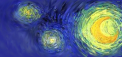




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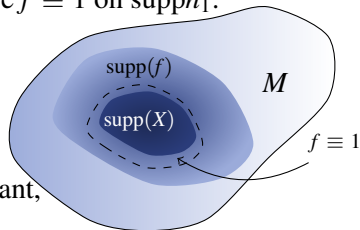
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- Abstractly,  $S'_M$  is a 1-form on  $\mathfrak{E}(M)$ .  
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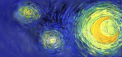




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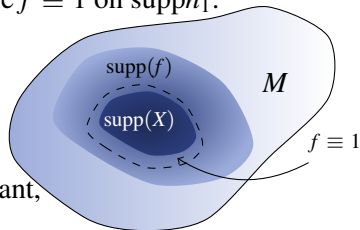
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- A **symmetry** of  $S$  is a **vector field** on  $\mathfrak{E}(M)$ ,  $X \in \mathfrak{X}(M)$  that characterizes the direction in which  $S$  is locally constant, i.e.  $\forall \varphi \in \mathfrak{E}(M): \langle S'_M(\tilde{g}), X(\tilde{g}) \rangle = 0$ .

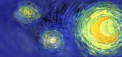




# Equations of motion and symmetries

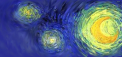
- The Euler-Lagrange derivative of  $S$  is defined by  $\langle S'_M(\tilde{g}), h_1 \rangle = \langle S_M(f)^{(1)}(\tilde{g}), h_1 \rangle$ , where  $f \equiv 1$  on  $\text{supp}h_1$ .
- Abstractly,  $S'_M$  is a 1-form on  $\mathfrak{E}(M)$ .  
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- Let  $\mathfrak{E}_S(M)$  denote the space of solutions of field equations. We want to characterise the space of functionals on  $\mathfrak{E}_S(M)$  which are invariant under all the local symmetries of  $S$ : **invariant on-shell functionals**  $\mathfrak{F}_S^{\text{inv}}(M)$ . In a finite dimensional case this space has a clear **homological interpretation**.





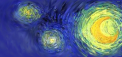
## Diffeomorphism invariance

- For GR symmetries are infinitesimal diffeomorphisms, i.e. elements of  $\mathfrak{X}(\mathcal{M}) \doteq \Gamma_c(TM)$ . Let us choose a sequence  $\vec{\xi} = (\xi_{\mathcal{M}})_{\mathcal{M} \in \text{Obj}(\mathbf{Loc})}$ ,  $\xi_{\mathcal{M}} \in \mathfrak{X}(\mathcal{M})$ .
- After applying the exponential map we obtain  $\alpha_{\mathcal{M}} \doteq \exp(\xi_{\mathcal{M}})$ .
- The exponentiated action of diffeomorphisms is given by:  
$$(\vec{\alpha}\Phi)_{(M,g)}(f)[\tilde{g}] = \Phi_{(M,g)}(\alpha_M^{-1} * f)[\alpha_M^* \tilde{g}].$$



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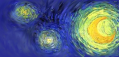
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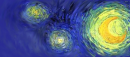


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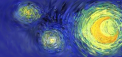
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- Example:  $\int R[\tilde{g}]f \, d \text{vol}_{(M,\tilde{g})}$  is diffeomorphism invariant, but  $\int R[\tilde{g}]f \, d \text{vol}_{(M,g)}$  is not.



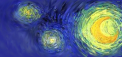
## Physical interpretation

- Let us fix  $\mathcal{M}$ . A test tensor  $f \in \mathcal{Tens}_c(\mathcal{M})$  corresponds to a concrete geometrical setting of an experiment, so for each  $\mathcal{M} \in \mathbf{Obj}(\mathbf{Loc})$ , we obtain a functional  $\Phi(f)$ , which depends covariantly on the geometrical data provided by  $f$ .



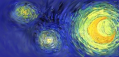
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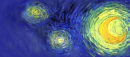


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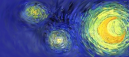
### New insight

Classical (or quantum) fields **generate physical quantities**, but a concrete observable quantity is obtained by evaluation on a test tensor. New concept: **evaluated fields**.



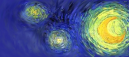
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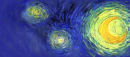
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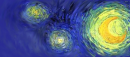
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- Let  $\mathcal{F}$  denote the subspace of  $\mathcal{C}^\infty(\text{Diff}_c(\mathcal{M}), \mathfrak{F}(\mathcal{M}))$  generated by elements of the form  $\Phi_f$  with respect to the pointwise product.





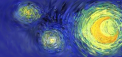
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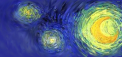
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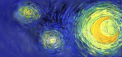
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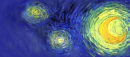
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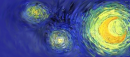
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- The underlying algebra of the BV complex is a graded algebra denoted by  $\mathcal{BV}$ .



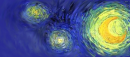
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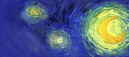
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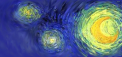
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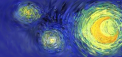
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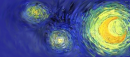
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- This induces a graded Poisson bracket  $\{., .\}$  on  $\mathcal{BV}$ . The BV-differential on  $Fld$  is given by:
$$(s\Phi)_{\mathcal{M}}(f) = \{\Phi_{\mathcal{M}}(f), S + \gamma\} + \Phi_{\mathcal{M}}(\mathcal{L}_C f),$$
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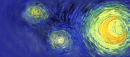
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- Gauge invariant observables are given by:  $\mathcal{F}_S^{\text{inv}} := H^0(s, \mathcal{BV})$ .



## Gauge fixing

- Gauge fixing is implemented by means of the so called gauge fixing fermion  $\Psi_f \in \mathcal{BV}$  with ghost number  $\#gh = 1$ .

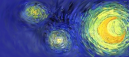


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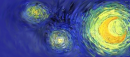
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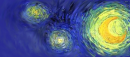
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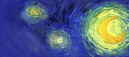
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- Note that  $H^0(s^\Psi, \alpha_\Psi(\mathcal{BV})) = H^0(s, \mathcal{BV}) = \mathcal{F}_S^{\text{inv}}$ .



## Equations of motion and Poisson bracket

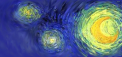
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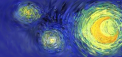
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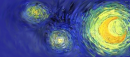
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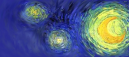
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- Using this input, we define the free Poisson bracket on  $\mathcal{BV}$

$$\{F, G\}_0^g \doteq \left\langle F^{(1)}, \Delta_g G^{(1)} \right\rangle \quad \Delta_g = \Delta_g^R - \Delta_g^A,$$



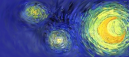
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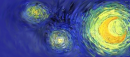
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- The deformation quantization of  $(\mathcal{BV}_{\mu\text{c}}, \{.,.\}_0^g)$  can be performed in the standard way, by introducing a  $\star$ -product:

$$(F \star_H G) \doteq m \circ \exp(\hbar \Gamma_{\omega_H})(F \otimes G) ,$$

where  $\Gamma_{\omega_H} \doteq \int dx dy \omega_H(x, y) \frac{\delta}{\delta\varphi(x)} \otimes \frac{\delta}{\delta\varphi(y)}$  and

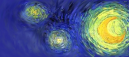
$\omega_H = \frac{i}{2} \Delta_g + H$  is the Hadamard 2-point function (satisfies the linearized EOM's in both arguments and the  $\mu\text{SC}$ ).



# Deformation quantization

- For a fixed  $\mathcal{M}$  we have a family of algebras  $\mathfrak{A}_H(\mathcal{M}) = (\mathcal{BV}_{\mu c}[[\hbar, \lambda]], \star_H)$ , numbered by possible choices of  $H$ . We can define  $\mathfrak{A}(\mathcal{M})$  to be an algebra consisting of families  $(F_H)$ , such that  $F_H = e^{\frac{\hbar}{2}\Gamma'_{H-H'}} F_{H'}$ , where  $\Gamma'_{H-H'} \doteq \int dx dy (H - H')(x, y) \frac{\delta^2}{\delta\varphi(x)\delta\varphi(y)}$  and the star product is given by

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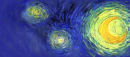
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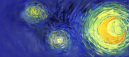
- This leads to a deformation quantization  $(\mathfrak{A}(\mathcal{M}), \star)$  of the space of fields.





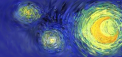
# Interaction

- In the next step we have to introduce the interaction, i.e. consider the algebras  $\mathfrak{A}_H(\mathcal{M}) = (\mathcal{BV}_{\mu c}[[\hbar, \lambda]], \star_H)$  and define on them the renormalized time-ordered products  $\cdot_{\mathcal{T}_H}$  by the Epstein-Glaser method.



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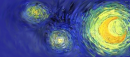
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- Interacting fields are obtained from free ones by the Bogoliubov formula:

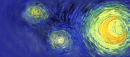
$$(R_V(\Phi))_{\mathcal{M}}(f) \doteq \left. \frac{d}{dt} \right|_{t=0} \mathcal{S}(V^g)^{\star-1} \star \mathcal{S}(V^g + t\Phi_{\mathcal{M}}(f)).$$



## Quantum observables

- In the framework of [K. Fredenhagen, K.R., CMP 2013], the gauge invariance of the  $S$ -matrix is guaranteed by the so called quantum master equation (QME):

$$\{e_{\mathcal{T}}^{V^g}, S_0^g\} = 0.$$



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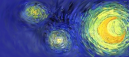
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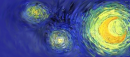
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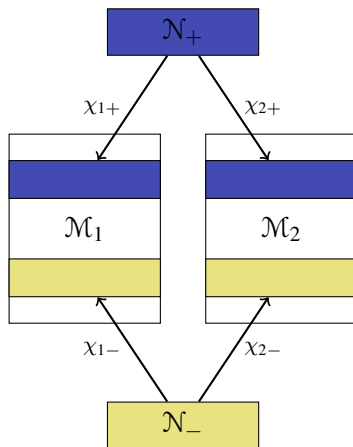
- If the QME holds, then gauge invariant quantum observables are recovered as the 0th cohomology of the quantum BV operator  $\hat{s} \doteq R_V^{-1} \circ \{., S_0\} \circ R_V$ . Equivalently,

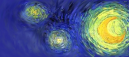
$$\hat{s}\Phi_{\mathcal{M}}(f) = \{., S_0^g + V^g\} + \Phi_{\mathcal{M}}(\mathcal{L}_{cf}) - i\hbar\Delta_{V^g}(\Phi_{\mathcal{M}}(f)).$$



# Relative Cauchy evolution

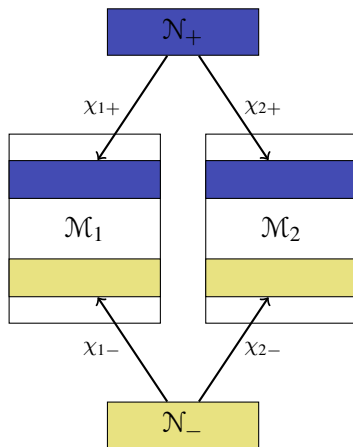
- Let  $\mathcal{N}_+$  and  $\mathcal{N}_-$  be two spacetimes that embed into two other spacetimes  $\mathcal{M}_1$  and  $\mathcal{M}_2$  around Cauchy surfaces, via causal embeddings given by  $\chi_{k,\pm}$ ,  $k = 1, 2$ .



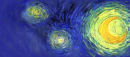


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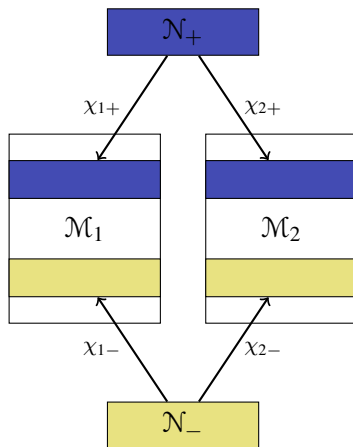


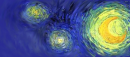




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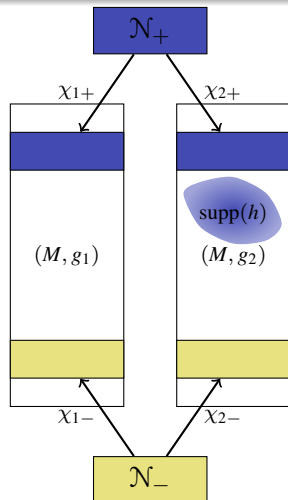
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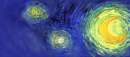




# Background independence

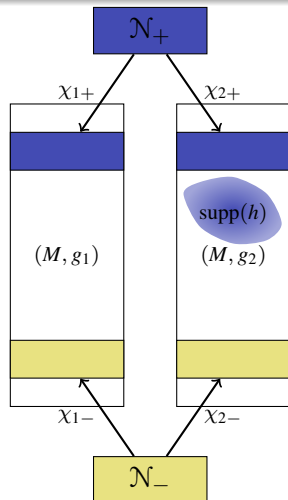
- Let  $\mathcal{M}_1 = (M, g_1)$  and  $\mathcal{M}_2 = (M, g_2)$ , where  $(g_1)_{\mu\nu}$  and  $(g_2)_{\mu\nu}$  differ by a (compactly supported) symmetric tensor  $h_{\mu\nu}$  with  $\text{supp}(h) \cap J^+(\mathcal{N}_+) \cap J^-(\mathcal{N}_-) = \emptyset$ ,

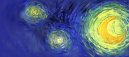




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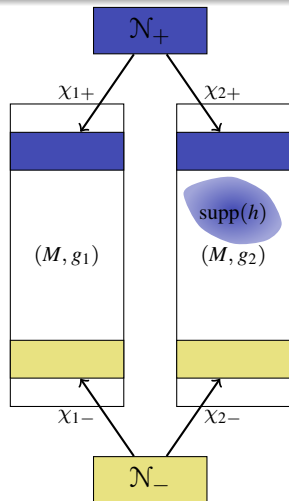
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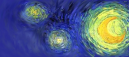




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- The infinitesimal version of the background independence is a condition that  $\Theta_{\mu\nu} = 0$ .





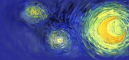
# Background independence

## Theorem [Brunetti, Fredenhagen, K.R. 2013]

The functional derivative  $\Theta_{\mu\nu}$  of the relative Cauchy evolution can be expressed, on-shell, as

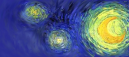
$$\Theta_{\mu\nu}(\Phi_{\mathcal{M}_1}(f)) \stackrel{o.s.}{=} [R_{V_1}(\Phi_{\mathcal{M}_1}(f)), R_{V_1}(T_{\mu\nu})]_{\star},$$

where  $T_{\mu\nu}$  is the stress-energy tensor of the extended action and one can define the time-ordered products in such a way that  $T_{\mu\nu} = 0$  holds, so the interacting theory is background independent.



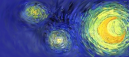
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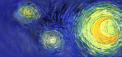
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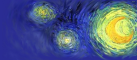
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- To quantize the theory, we make a tentative split into a free and interacting theory. We quantize the free theory first and then use the Epstein-Glaser renormalization to introduce the interaction.
- We have shown, using the relative Cauchy evolution, that our theory is background independent, i.e. independent of the split into free and interacting part.



Thank you for your attention!