

Functional analytic aspects of renormalization on Lorentzian manifolds

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Outline of the talk





2 Free scalar field



3 Interaction and renormalization



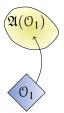
Motiviation: AQFT

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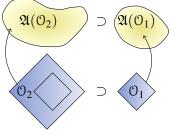
- A convenient framework to investigate conceptual problems in QFT is the Algebraic Quantum Field Theory.
- It started as the axiomatic framework of Haag-Kastler [Haag & Kastler 64]: a model is defined by associating to each region O of Minkowski spacetime (M ≐ (R⁴, η) η = diag(1, -1, -1, -1)), the C*-algebra 𝔄(O) of observables that can be measured in O.





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- A convenient framework to investigate conceptual problems in QFT is the Algebraic Quantum Field Theory.
- It started as the axiomatic framework of Haag-Kastler [Haag & Kastler 64]: a model is defined by associating to each region 0 of Minkowski spacetime (M ≐ (R⁴, η) η = diag(1, -1, -1, -1)), the C*-algebra 𝔄(0) of observables that can be measured in 0.
- The physical notion of subsystems is realized by the condition of isotony, i.e.: O₂ ⊃ O₁ ⇒ A(O₂) ⊃ A(O₁). We obtain a net of algebras.





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- A complex *- algebra 𝔅 is an algebra over the field of complex numbers, together with a map, * : 𝔅 → 𝔅, called an involution. The image of an element A ∈ 𝔅 under the involution is written A*. Involution is required to have the following properties:



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- Here, a topological *- algebra is a topological vector space, which is a *- algebra and the product is sequentially continuous.



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 - Spacetime *M*: a smooth manifold with a smooth pseudo-Riemannian metric (a smooth section *g* ∈ Γ(*T***M* ⊗ *T***M*), s.t. for every *p* ∈ *M*, *g_p* is a symmetric non degenerate bilinear form) of the Lorentz signature (we choose the convention (+, −, −, ..., −)). We also assume *M* to be globally hyperbolic (has a Cauchy surface).



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 - Configuration space: space of smooth sections of some vector bundle E ^π→ M over M, for the scalar field: ε(M) ≡ C[∞](M, ℝ).
 - Action: a map $S_M : \mathcal{D}(M) \to \mathcal{C}^{\infty}(\mathcal{E}(M), \mathbb{R})$, where $\mathcal{D}(M) \equiv \mathcal{C}^{\infty}_c(M, \mathbb{R})$ are compactly supported smooth functions. An example action:

$$S_M(f)(\varphi) = \frac{1}{2} \int (\nabla_\mu \varphi \nabla^\mu \varphi - m^2 \varphi^2)(x) f(x) d\mu(x), \text{ where } f \in \mathcal{D}(M) \text{ (cutoff)}, \varphi \in \mathcal{E}(M), \mu(x) \text{ is the volume form on } M.$$



Functionals

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- Let U ⊆ ε(M) open and F : U → ℝ. The derivative of F at φ in the direction of h is defined as
 F⁽¹⁾(φ)(h) = lim_{t→0} 1/t (F(φ + th) - F(φ)) (if exists)
 F is called differentiable if F⁽¹⁾(φ)(h) exists ∀φ ∈ U, h ∈ ε(M).

It is called continuously differentiable (in the sense of Bastiani) if it is differentiable on U and

 $F^{(1)}: U \times \mathcal{E}(M) \to \mathbb{R}, (\varphi, h) \mapsto F^{(1)}(\varphi)(h)$ is continuous.





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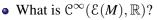
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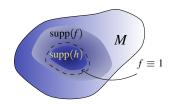
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- The support of $F \in \mathcal{C}^{\infty}(\mathcal{E}(M), \mathbb{R})$ is defined as:

$$\begin{split} \operatorname{supp} F &= \{ x \in M | \forall \text{ neighbourhoods } U \text{ of } x \exists \varphi, \psi \in \mathcal{E}(M), \\ \operatorname{supp} \psi \subset U \text{ such that } F(\varphi + \psi) \neq F(\varphi) \} \;. \end{split}$$



Equations of motion

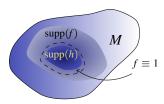
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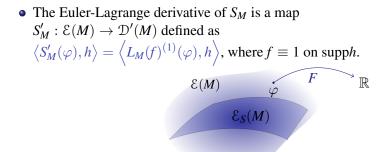
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- EOM determines a subspace of ε(M) denoted by ε_S(M) (on-shell configurations).



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Definition

Let $u \in \mathcal{D}'(\Omega)$, the wavefront set WF(u) is the complement in $\Omega \times \mathbb{R}^n \setminus \{0\}$ of the set of $(x, \xi) \in \Omega \times \mathbb{R}^n \setminus \{0\}$ such that there exist $f \in \mathcal{D}(\Omega)$ with f(x) = 1 and an open conic neighborhood C of ξ , with

$$\sup_{\xi\in C} (1+|\xi|)^N |\widehat{f\cdot u}(\xi)| < \infty \qquad \forall N\in \mathbb{N}_0.$$



Definition

A functional $F \in C^{\infty}(\mathcal{E}(M), \mathbb{R})$ is called additive if

$$F(\varphi_1 + \varphi_2 + \varphi_3) = F(\varphi_1 + \varphi_2) + F(\varphi_2 + \varphi_3) - F(\varphi_2),$$

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Input from microlocal analysis



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- Green's functions of a normally hyperbolic operator have some particular singularities structure.
- We use these facts to define the algebra 𝔅(𝒴) by introducing a ★-product on a certain subspace of 𝔅[∞](𝔅(𝒴), ℝ).



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- Their difference is the causal propagator $\Delta \doteq \Delta^R \Delta^A$.



Propagators and Green's functions

WF(Δ) = {(x, k; x', −k') ∈ T^{*}M²|(x, k) ~ (x', k')}, where ~ means that there is a causal curve connecting x and x', and k' is the parallel transport of k along it.



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- We can always decompose Δ to positive and negative frequency parts: $\frac{i}{2}\Delta = \Delta_+ H$, i.e.:

$$WF(\Delta_{+}) = \{(x,k;x',-k') \in \dot{T}M^{2} | (x,k) \sim (x',k'), k \in (\overline{V}_{+})_{x} \},\$$

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• We can also define the Feynman propagator:

$$\Delta_F = \frac{i}{2} (\Delta^A + \Delta^R) + H.$$



*-product

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Definition

A functional F is called microcausal ($F \in \mathfrak{F}_{\mu c}(M)$) if

$$\operatorname{WF}(F^{(n)}(\varphi)) \subset \Xi_n, \quad \forall n \in \mathbb{N}, \ \forall \varphi \in \mathcal{E}(M),$$

 $\Xi_n \doteq T^*M^n \setminus \{(x_1, \ldots, x_n, k_1, \ldots k_n) | k_i \in (\overline{V}_+)_{x_i} \cup (\overline{V}_-)_{x_i}, i = 1 \ldots n\}.$



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• Define the *-product (deformation of the pointwise product):

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• Introduce on $\mathfrak{F}_{\mu c}(M)$ a topology τ that controls the WF sets of the derivatives of functionals.





Definition

The free QFT is defined by assigning to $\mathcal{O} \subset M$

 $\mathfrak{A}_{0}(\mathfrak{O}) \doteq (\mathfrak{F}_{\mu \mathbf{c}}(\mathfrak{O}), \tau, \star, \ast) \,,$

where $F^*(\varphi) \doteq \overline{F(\varphi)}$ and $\mathfrak{F}_{\mu c}(\mathfrak{O})$ is the space of microcausal functionals supported in \mathfrak{O} .



Time-ordered product

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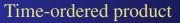
Time-ordered product

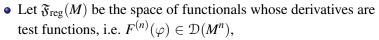
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• Formally it would correspond to the operator of convolution with the oscillating Gaussian measure "with covariance $\hbar \Delta_F$ ",

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• The time-ordering operator T is defined as:

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• Define the time-ordered product $\cdot_{\mathfrak{T}}$ on $\mathfrak{F}_{reg}(M)[[\hbar]]$ by:

$$F \cdot_{\mathfrak{T}} G \doteq \mathfrak{T}(\mathfrak{T}^{-1}F \cdot \mathfrak{T}^{-1}G)$$



We now have an algebraic structure with two products
 (𝔅_{reg}(M)[[ħ]], *, ·τ), where * is non-commutative, ·τ is
 commutative and they are related by a causal relation:

$$F \cdot_{\mathfrak{T}} G = F \star G \,,$$

if supp*F* is later than supp*G*. Hence the name "time-ordered".

Interaction

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• Interaction is a functional $V \in \mathfrak{F}_{reg}(M)$. Using the commutative product $\cdot_{\mathfrak{T}}$ we define the S-matrix:

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 Because of the WF set properties of Δ_F, the time-ordered product ·_τ is not well defined on local, non-constant functionals, but the physical interaction is usually local!

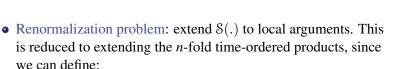


Renormalization problem

• Renormalization problem: extend S(.) to local arguments. This is reduced to extending the *n*-fold time-ordered products, since we can define:

$$\mathcal{S}(V) = \sum_{n=0}^{\infty} \frac{1}{n!} \mathcal{T}^n(V, ..., V) \,.$$

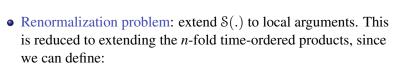
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- To extend \mathcal{T}^n to arbitrary local functionals we use the causal approach of Epstein and Glaser (causal perturbation theory).



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- Starting element. $T^0 = 0$, $T^1 = id$.
- **Supports.** supp $\mathcal{T}^n(F_1,\ldots,F_n) \subset \bigcup \operatorname{supp} F_i$.
- Solution Causal factorization property. If the supports of $F_1 ldots F_i$ are later than the supports of F_{i+1}, \ldots, F_n , then we have:

$$\mathfrak{T}^n(F_1\otimes\cdots\otimes F_n)=\mathfrak{T}^i(F_1\otimes\cdots\otimes F_i)\star\mathfrak{T}^{n-i}(F_{i+1}\otimes\cdots\otimes F_n).$$



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By the theorem of Epstein and Glaser we know that the extension exists, but is not unique. The theorem is proved inductively (in n) and at each step the problem is reduced to an extension of a real valued distribution.



• For simplicity, consider $M = \mathbb{M} \doteq (\mathbb{R}^4, \eta)$, where $\eta = \text{diag}(1, -1, -1, -1)$.



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• distribution: $\widetilde{S_{\alpha}} \doteq \sum_{\Gamma \in \mathfrak{G}_{\alpha}} \frac{\hbar^{|E(\Gamma)|}}{\operatorname{Sym}(\Gamma)} \widetilde{S_{\Gamma}}$, where the sum is taken over

 \mathcal{G}_{α} , the set of (non-tadpole) graphs with $n = \dim(\alpha)$ vertices and $\frac{|\alpha|}{2}$ lines such that there are α_i lines joining at vertex *i* and $\operatorname{Sym}(\Gamma) \in \mathbb{N}$ is the so called symmetry factor of the graph Γ .



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• Each $\widetilde{S_{\Gamma}} \doteq \prod_{e \in E(\Gamma)} \Delta_F(x_{e,i}, i \in \partial_e)$ is a well defined distribution

on $\mathcal{D}'((\mathbb{M}^2 \setminus \text{Diag})^{|E(\Gamma)|})$ (Diag denotes the diagonal).



• The *n*-fold time-ordered product can then be written as

$$F_1 \cdot_{\mathfrak{T}} \cdots \cdot_{\mathfrak{T}} F_n = \sum_{\alpha \in \mathbb{N}^n} \left\langle \widetilde{S_{\alpha}}, \boldsymbol{\delta}^{\alpha} \left(F_1 \otimes \cdots \otimes F_n \right) \right\rangle$$



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• Functional derivatives of a local functional have the form

$$F^{(l)}[\varphi](x_1,\ldots,x_l) = \int dz \sum_j f_j[\varphi](z) p_j(\partial_{x_1},\ldots,\partial_{x_l}) \prod_{i=1}^l \delta(z-x_i)$$

with polynomials p_j and φ -dependent test functions $f_j[\varphi]$.



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• Note that functional derivatives $\frac{\delta}{\delta\varphi(x_{e,v})}$ are associated to vertices v of the graph (see picture), and we get one derivative for each edge e adjacent at v, so the variables "x" in the formula above are also numbered by $v \in V(\Gamma)$ and $e \in E(\Gamma)$.



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- We can move the partial derivatives ∂_{x_{e,v}} by formal partial integration to the distribution S_Γ.



Extensions of distributions

 Next we integrate over the delta distributions, which amounts to the pullback with respect to ρ_Γ : M^{|V(Γ)|} → M^{2|E(Γ)|},

$$(\rho_{\Gamma}(z))_{e,v} = z_v \quad \text{if } v \in \partial e \,.$$



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• Let *p* be a polynomial in the partial derivatives $\partial_{x_{e,v}}, v \in \partial e$. The pullback ρ_{Γ}^* of $\widetilde{pS_{\Gamma}}$ is well defined on $\mathbb{M}^{|V(\Gamma)|} \setminus \text{DIAG}$, where DIAG is the large diagonal:

$$\mathsf{DIAG} = \left\{ z \in \mathbb{M}^{|V(\Gamma)|} | \exists v, w \in V(\Gamma), v \neq w : z_v = z_w \right\} \,.$$



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The problem of renormalization now amounts to finding the extensions of ρ^{*}_ΓpS̃_Γ to everywhere defined distributions S_{Γ,p} ∈ D'(M^{|V(Γ)|}).



• The construction is inductive. We assume that graphs with *k* < *n* vertices are renormalized (corresponding extensions of distributions are constructed), so the problem of renormalizing graphs with *n* vertices reduces to extending distributions defined everywhere outside the origin.



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- The existence and uniqueness of extensions \dot{t} can be answered in terms of Steinmann's scaling degree of t,

$$\begin{split} \mathrm{sd}(u) &:= \inf\{\omega \in \mathbb{R} \mid \lim_{\rho \downarrow 0} \rho^{\omega} \, u(\rho x) = 0\}, \\ & u \in \mathcal{D}'(\mathbb{R}^n) \quad \mathrm{or} \quad u \in \mathcal{D}'(\mathbb{R}^n \setminus \{0\}) \;. \end{split}$$



Theorem (Steinmann 71, Brunetti Fredenhagen 2000)

For $\lambda \in \mathbb{R}$ let

$$\mathcal{D}_{\lambda}(\mathbb{R}^{n}) := \{ f \in \mathcal{D}(\mathbb{R}^{n}) \, | \, (\partial^{\alpha} f)(0) = 0 \ \forall |\alpha| \le \lambda \}$$
(1)

(in particular $\mathcal{D}_{\lambda}(\mathbb{R}^n) = \mathcal{D}(\mathbb{R}^n)$ if $\lambda < 0$) and let $\mathcal{D}'_{\lambda}(\mathbb{R}^n)$ be the corresponding space of distributions. A distribution $t \in \mathcal{D}'(\mathbb{R}^n \setminus \{0\})$ with scaling degree sd(t) has a unique extension $\overline{t} \in \mathcal{D}'_{\lambda}(\mathbb{R}^n)$, $\lambda = \operatorname{sd}(t) - n$, which satisfies the condition sd(\overline{t}) = sd(t).

An extension to a distribution on the full space $\mathcal{D}(\mathbb{M}^{n-1})$ can be therefore defined by a choice of the projection:

$$W: \mathcal{D}(\mathbb{M}^{n-1}) \to \mathcal{D}_{\lambda}(\mathbb{M}^{n-1}).$$



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- Elements of \mathcal{R} are maps $Z : \mathcal{F}_{loc}[[\hbar]] \to \mathcal{F}_{loc}[[\hbar]]$ satisfying:



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- Z(A+B+C) = Z(A+B) Z(B) + Z(B+C) if supp $(A) \cap$ supp $(C) = \emptyset$,
- They don't depend explicitly on the field configuration φ .



Commutative product



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- We define $\mathfrak{T}_{\mathbf{r}} = (\oplus_n \mathfrak{T}_{\mathbf{r}}^n) \circ \beta$ and set:

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which is an associative, commutative product on $\mathcal{T}_{r}(\mathfrak{F}(M))$.

• The renormalized QFT is a structure with two products $\mathfrak{O} \mapsto \mathfrak{A}(\mathfrak{O}) = (\mathfrak{I}_r(\mathfrak{F}(\mathfrak{O})), \tau, \star, \cdot_{\mathfrak{I}_r}).$





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- Construction of QFT models on curved spacetimes can be put on solid mathematical grounds using the functional approach.
- The basic structure is a net of non-commutative topological *-algebras with the additional commutative product.
- Analytic tools involve calculus on locally convex topological vector space and methods of microlocal analysis.





Thank you for your attention!