

Batalin-Vilkovisky formalism and General Relativity

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BV formalism

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Preliminaries

Gravity

Conclusions

- 1 Preliminaries
 - Kinematical structure
 - Smooth calculus in lcv's
 - Equations of motion and symmetries

- 2 Gravity
 - Action and symmetries
 - BV complex on natural transformations



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Preliminaries

Gravity

Conclusions



- Very successful in perturbative quantum field theory



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Preliminaries

Gravity

Conclusions



- Very successful in perturbative quantum field theory
- Implements gauge fixing in a general framework



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Preliminaries

Gravity

Conclusions



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- Uses powerful methods of homological algebra [Henneaux, ...]



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Preliminaries

Gravity

Conclusions



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- **Not very well understood for infinite dimensional spaces**



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Preliminaries

Gravity

Conclusions



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Preliminaries

Gravity

Conclusions



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- Completely neglects topological and functional-analytic aspects
- **Needs more fundamental structural understanding**



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Preliminaries

Gravity

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*Batalin-Vilkovisky formalism in the
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Preliminaries

Gravity

Conclusions

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Preliminaries

Gravity

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Categories

BV formalism

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Preliminaries

Kinematical
structure

Smooth
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levs

Equations
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and sym-
metries

Gravity

Conclusions



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Rejzner**Loc**

Obj(**Loc**): all four-dimensional, globally hyperbolic oriented and time-oriented spacetimes (M, \mathbf{g}) .

Preliminaries

Kinematical
structureSmooth
calculus in
levsEquations
of motion
and sym-
metries

Gravity

Conclusions



BV formalism

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Preliminaries

Kinematical
structureSmooth
calculus in
levsEquations
of motion
and sym-
metries

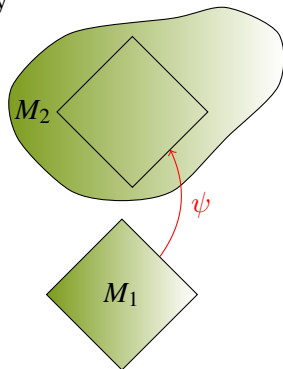
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Conclusions

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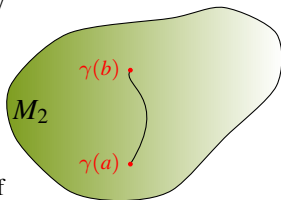
Morphisms: Isometric embeddings that fulfill:



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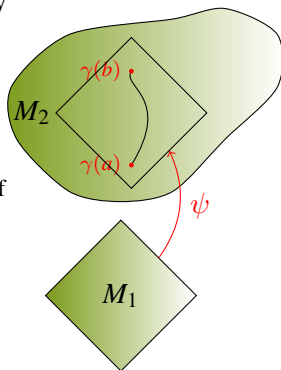


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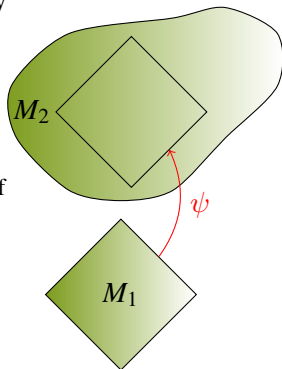


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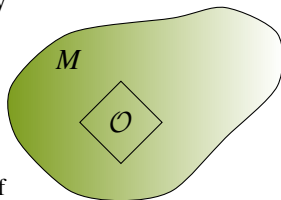


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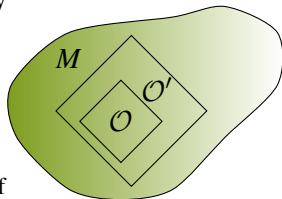


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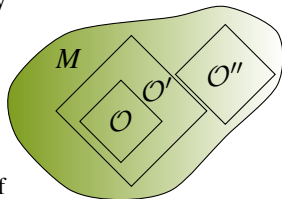


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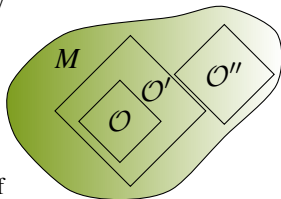


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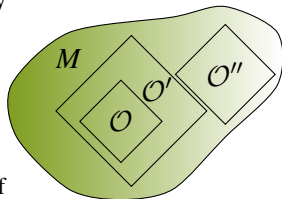


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BV formalism

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Preliminaries

Kinematical
structureSmooth
calculus in
lcvsEquations
of motion
and sym-
metries

Gravity

Conclusions

In our formulation with a physical system we associate:

- The configurations space $\mathfrak{E}(M)$ of all fields of the theory. \mathfrak{E} is a **contravariant** functor from **Loc** (spacetimes) to **Vec** (lcvs). For the scalar field: $\mathfrak{E}(M) = \mathcal{C}^\infty(M)$.



BV formalism

Katarzyna
Rejzner

Preliminaries

Kinematical
structure

Smooth
calculus in
lcvs

Equations
of motion
and sym-
metries

Gravity

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- The space of compactly supported fields $\mathfrak{E}_c(M)$. \mathfrak{E}_c is a **covariant** functor from **Loc** to **Vec**.



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Preliminaries

Kinematical
structureSmooth
calculus in
lcvsEquations
of motion
and sym-
metries

Gravity

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- $\mathfrak{D} : \mathbf{Loc} \rightarrow \mathbf{Vec}$ a covariant functor that assigns to M the space of compactly supported test functions $\mathfrak{D}(M)$.



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- The space of **smooth, compactly supported** functionals on $\mathfrak{E}(M)$. This also defines a covariant functor $\mathfrak{F} : \mathbf{Loc} \rightarrow \mathbf{Vec}$ (+ regularity conditions: local, microcausal, ...).



BV formalism

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Preliminaries

Kinematical
structure

Smooth
calculus in
levs

Equations
of motion
and sym-
metries

Gravity

Conclusions

- Smoothness understood in the sense of calculus on locally convex vector spaces.



BV formalism

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Preliminaries

Kinematical
structureSmooth
calculus in
leversEquations
of motion
and sym-
metries

Gravity

Conclusions

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- The **support** of a functional $F \in \mathcal{C}^\infty(\mathfrak{E}(M))$

$$\text{supp } F = \{x \in M \mid \forall \text{ neighbourhoods } U \text{ of } x \exists \phi, \psi \in \mathfrak{E}(M), \\ \text{supp } \psi \subset U \text{ such that } F(\phi + \psi) \neq F(\phi)\} .$$



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- F is **local** if it is of the form: $F(\phi) = \int_M f(j_x(\phi)) d\mu(x)$, where f is a function on the jet bundle over M and $j_x(\phi)$ is the jet of ϕ at the point x . $\mathfrak{F}_{\text{loc}}$ is a subfunctor of \mathfrak{F} .



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- In this talk we restrict ourselves to *multilocal functionals*, which are defined as finite sums of finite products of local functionals.



BV formalism

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Preliminaries

Kinematical
structureSmooth
calculus in
levsEquations
of motion
and sym-
metries

Gravity

Conclusions

- The dynamics is introduced by a **generalized Lagrangian** L which is a natural transformation between functors \mathfrak{D} and $\mathfrak{F}_{\text{loc}}$, s.t.: $\text{supp}(L_M(f)) \subseteq \text{supp}(f)$, and $L_M(\bullet)$ is additive in f . The **action** $S(L)$ is an equivalence class of Lagrangians. We say that $L_1 \sim L_2$ if $\forall f \in \mathfrak{D}(M), M \in \mathbf{Loc}$:

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BV formalism

Katarzyna
Rejzner

Preliminaries

Kinematical
structure

Smooth
calculus in
levs

Equations
of motion
and sym-
metries

Gravity

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- For example: $L_M(f) = \int_M \left(\frac{1}{2} \phi^2 + \frac{1}{2} \nabla_\mu \phi \nabla^\mu \phi \right) f \, d\text{vol}_M.$



BV formalism

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Preliminaries

Kinematical
structure

Smooth
calculus in
levs

Equations
of motion
and sym-
metries

Gravity

Conclusions

- Vector fields X on $\mathfrak{E}(M)$ (trivial infinite dimensional manifold) can be considered as maps from $\mathfrak{E}(M)$ to $\mathfrak{E}(M)$.



BV formalism

Katarzyna
Rejzner

Preliminaries

Kinematical
structureSmooth
calculus in
levsEquations
of motion
and sym-
metries

Gravity

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- We restrict ourselves to smooth maps X with image in $\mathfrak{E}_c(M)$. They act on $\mathfrak{F}(M)$ as derivations:
$$\partial_X F(\phi) := \langle F^{(1)}(\phi), X(\phi) \rangle$$



BV formalism

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Rejzner

Preliminaries

Kinematical
structureSmooth
calculus in
lefsEquations
of motion
and sym-
metries

Gravity

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$$\partial_X F(\phi) := \langle F^{(1)}(\phi), X(\phi) \rangle$$
- We consider only the multilocal (products of local vector fields and local functionals) vector fields with compact support.



BV formalism

Katarzyna
Rejzner

Preliminaries

Kinematical
structure

Smooth
calculus in
levs

Equations
of motion
and sym-
metries

Gravity

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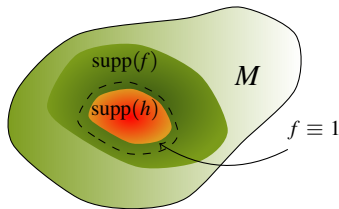
$$\partial_X F(\phi) := \langle F^{(1)}(\phi), X(\phi) \rangle$$
- We consider only the multilocal (products of local vector fields and local functionals) vector fields with compact support.
- The space of vector fields with above properties is denoted by $\mathfrak{V}(M)$. \mathfrak{V} becomes a (covariant) functor by setting:

$$\mathfrak{V}\chi(X) = \mathfrak{E}_c\chi \circ X \circ \mathfrak{E}\chi.$$



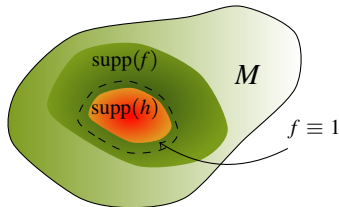
- The Euler-Lagrange derivative of S is a natural transformation $S' : \mathfrak{E} \rightarrow \mathfrak{D}'$ defined by:

$$\langle S'_M(\varphi), h \rangle = \langle L_M(f)^{(1)}(\varphi), h \rangle$$
 with $f \equiv 1$ on $\text{supp}h$. The field equation is: $S'_M(\varphi) = 0$.



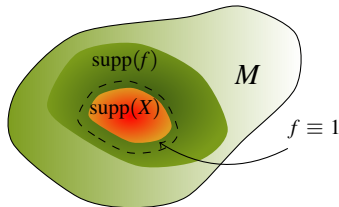
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- A vector field $X \in \mathfrak{V}(M)$ is called a **symmetry** of the action S if it holds $\forall \varphi \in \mathfrak{E}(M)$:

$$0 = \langle S'_M(\varphi), X(\varphi) \rangle = \partial_X(S_M)(\varphi) =: \delta_S(X)(\varphi).$$



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BV formalism

Katarzyna
Rejzner

Preliminaries

Kinematical
structure

Smooth
calculus in
levs

Equations
of motion
and sym-
metries

Gravity

Conclusions

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A **symmetry** of the action: $0 = \partial_X(S_M)(\varphi) =: \delta_S(X)(\varphi)$.
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- Space of solutions: $\mathfrak{E}_S(M) \subset \mathfrak{E}(M)$. Functionals that vanish on $\mathfrak{E}_S(M)$: $\mathfrak{F}_0(M)$. Assume that they are of the form: $\delta_S(X)$ for some $X \in \mathfrak{V}(M)$.



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- Functionals on $\mathfrak{E}_S(M)$: $\mathfrak{F}_S(M) \doteq \mathfrak{F}(M)/\mathfrak{F}_0(M) = H_0(\delta_S)$.



BV formalism

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Preliminaries

Kinematical
structureSmooth
calculus in
levsEquations
of motion
and sym-
metries

Gravity

Conclusions

- In the absence of symmetries the graded algebra $\bigwedge \mathfrak{V}(M)$ with the differential δ_S provides the resolution of $\mathfrak{F}_S(M) = \mathfrak{F}(M)/\mathfrak{F}_0(M)$, called the **Koszul resolution**.



BV formalism

Katarzyna
Rejzner

Preliminaries

Kinematical
structureSmooth
calculus in
leavesEquations
of motion
and sym-
metries

Gravity

Conclusions

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$$\dots \rightarrow \bigwedge^2 \mathfrak{W}(M) \xrightarrow{1} \mathfrak{W}(M) \xrightarrow[0]{\delta_S} \mathfrak{F}(M) \rightarrow 0$$



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BV formalism

Katarzyna
Rejzner

Preliminaries

Kinematical
structureSmooth
calculus in
levsEquations
of motion
and sym-
metries

Gravity

Conclusions

- Vector fields in $\mathfrak{V}(M)$ correspond to objects called in physics *antifields*. The grading of Koszul complex is called *antifield number* #af.



BV formalism

Katarzyna
Rejzner

Preliminaries

Kinematical
structureSmooth
calculus in
levsEquations
of motion
and sym-
metries

Gravity

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BV formalism

Katarzyna
Rejzner

Preliminaries

Kinematical
structureSmooth
calculus in
levsEquations
of motion
and sym-
metries

Gravity

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- Derivation δ_S is not inner with respect to $\{.,.\}$, but locally it can be written as $\delta_S X = \{X, L_M(f)\}$ for $f \equiv 1$ on $\text{supp}X$, $X \in \mathfrak{V}(M)$.



1 Preliminaries

- Kinematical structure
- Smooth calculus in lcv's
- Equations of motion and symmetries

2 Gravity

- Action and symmetries
- BV complex on natural transformations



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- The Einstein-Hilbert Lagrangian reads:

$$L_{(M,g)}(f)(h) \doteq \int R[\tilde{g}]f \, d \operatorname{vol}_{(M,\tilde{g})}, \quad \tilde{g} = g + h, \text{ where } h \in U_g \subset \mathfrak{E}(M) \text{ and } U_g \text{ is an open neigh. of } g, \text{ s.t. } \tilde{g} \text{ is a Lorentz metric of signature } (-+++).$$



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- The most general nontrivial local symmetries can be written as elements of $\mathfrak{G}(M) := C_{\text{ml}}^\infty(\mathfrak{E}(M), \mathfrak{X}_c(M))$ ("ml" stands for "multilocal"). With the action ρ of $\mathfrak{G}(M)$ on $F \in \mathfrak{F}(M)$:

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$$\rho_M(Q)(h) = \left\langle F^{(1)}(h), \mathcal{L}_{Q(h)}\tilde{g} \right\rangle$$
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BV formalism

Katarzyna
Rejzner

Preliminaries

Gravity

Action and
symme-
triesBV
complex
on natural
transformations

Conclusions

With the Lie algebra action of $\mathfrak{g}_c(M)$ on $\mathfrak{F}(M)$ one associates the **Chevalley-Eilenberg complex**. This is the graded algebra of smooth compactly supported multilocal (products of local) maps $\mathfrak{CE}(M) \doteq C_{\text{ml}}^\infty(\mathfrak{E}(M), \Lambda \mathfrak{g}'(M))$.



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$$\begin{aligned} \gamma_M : \quad \Lambda^q \mathfrak{g}'(M) \otimes \mathfrak{F}(M) &\rightarrow \Lambda^{q+1} \mathfrak{g}'(M) \otimes \mathfrak{F}(M), \\ (\gamma_M \omega)(\xi_0, \dots, \xi_q) &\doteq \sum_{i=0}^q (-1)^i \partial_{\rho_M(\xi_i)} (\omega(\xi_0, \dots, \hat{\xi}_i, \dots, \xi_q)) + \\ &+ \sum_{i < j} (-1)^{i+j} \omega([\xi_i, \xi_j], \dots, \hat{\xi}_i, \dots, \hat{\xi}_j, \dots, \xi_q), \end{aligned}$$

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and extended by continuity. In particular for $F \in \mathfrak{F}(M)$ we have: $(\gamma F)(X) = \partial_{\rho(X)} F$ and $\gamma F = 0$ if $F \in \mathfrak{F}^{\text{inv}}(M)$.



BV formalism

Katarzyna
Rejzner

Preliminaries

Gravity

Action and
symme-
tries

BV
complex
on natural
transformations

Conclusions

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BV formalism

Katarzyna
Rejzner

Preliminaries

Gravity

Action and
symmetries

BV
complex
on natural
transformations

Conclusions

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BV formalism

Katarzyna
Rejzner

Preliminaries

Gravity

Action and
symmetries

BV
complex
on natural
transformations

Conclusions

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BV formalism

Katarzyna
Rejzner

Preliminaries

Gravity

Action and
symmetries

BV
complex
on natural
transformations

Conclusions

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- Now we construct the Koszul-Tate resolution of the algebra $\mathcal{CE}_S(M)$.



- Let $\mathcal{BV}(M)$ be the subset of $S^\bullet \text{Der}(\mathcal{CE}(M))$ (graded symmetric powers) consisting of derivations that can be written as multilocal compactly supported maps on $\mathcal{E}(M)$. The corresponding grading is denoted by $\#gh$ (**ghost number**).



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- We define the BV differential: $sF = \{F, L_M(f) + \theta_M(f)\}$.



BV formalism

Katarzyna
Rejzner

Preliminaries

Gravity

Action and
symmetries

BV
complex
on natural
transformations

Conclusions

- The full BV complex reads explicitly:

$$\mathfrak{BV}(M) = \mathcal{C}_{\text{ml}}^{\infty} \left(\mathfrak{E}(M), \bigwedge \mathfrak{E}_c(M) \hat{\otimes} \bigwedge \mathfrak{g}'(M) \hat{\otimes} S^{\bullet} \mathfrak{g}_c(M) \right)$$



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BV complex

BV formalism

Katarzyna
Rejzner

Preliminaries

Gravity

Action and
symmetries

BV
complex
on natural
transformations

Conclusions

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- The gauge invariant observables are given by:

$$H^0(\mathfrak{B}\mathfrak{Y}(M), s) = H^0(\mathfrak{CE}_S(M), s^{(0)}) = \mathfrak{F}_S^{\text{inv}}(M)$$





BV complex on the fixed background

BV formalism

Katarzyna
Rejzner

Preliminaries

Gravity

Action and
symmetries

BV
complex
on natural
transformations

Conclusions

Problem

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Solution

We define the algebra of fields as: $Fld = \bigoplus_{k=0}^{\infty} \text{Nat}(\mathfrak{E}_c^k, \mathfrak{B}\mathfrak{V})$. The action of symmetries on natural transformations $\Phi \in \text{Nat}(\mathfrak{E}_c, \mathfrak{F})$:

$$(\rho_M(X)\Phi_M)(f) := \partial_{\rho_M(X)}(\Phi_M(f)) + \Phi_M(\rho_M(X)f), \quad X \in \mathfrak{X}(M).$$



BV formalism

Katarzyna
Rejzner

Preliminaries

Gravity

Action and
symmetries

BV
complex
on natural
transformations

Conclusions

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Fields as natural transformations

BV formalism

Katarzyna
Rejzner

Preliminaries

Gravity

Action and
symmetries

BV
complex
on natural
transformations

Conclusions

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- Physical picture: A field tells us how to compare the observations localized in different regions of a spacetime M in the absence of symmetries.





Fields as natural transformations

BV formalism

Katarzyna
Rejzner

Preliminaries

Gravity

Action and
symmetries

BV
complex
on natural
transformations

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- In classical gravity we understand physical quantities not as pointwise objects but rather as something defined on all the spacetimes in a coherent way.





Fields as natural transformations

BV formalism

Katarzyna
Rejzner

Preliminaries

Gravity

Action and
symmetries

BV
complex
on natural
transformations

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- In the framework of locally covariant field theory (Brunetti-Fredenhagen-Verch) fields are natural transformation between certain functors.
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- In classical gravity we understand physical quantities not as pointwise objects but rather as something defined on all the spacetimes in a coherent way.
- For example scalar curvature R is invariant in this sense, but $R(x)$ (curvature at a given point) not.



- The set Fld becomes a graded algebra if we equip it with a graded product defined as:

$$\begin{aligned}
 (\Phi\Psi)_M(f_1, \dots, f_{p+q}) &= \\
 &= \frac{1}{p!q!} \sum_{\pi \in P_{p+q}} \Phi_M(f_{\pi(1)}, \dots, f_{\pi(p)}) \Psi_M(f_{\pi(p+1)}, \dots, f_{\pi(p+q)}) .
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- The BV-differential on Fld is now given by:

$$(s\Phi)_M(f) := s_0(\Phi_M(f)) + (-1)^{|\Phi|} \Phi_M(\rho_M(\cdot)f),$$

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- The 0-cohomology of s is **nontrivial**, since it contains for example the Riemann tensor contracted with itself, smeared with a test function:

$$\Phi_{(M,g)}(f)(h) = \int_M R_{\mu\nu\alpha\beta}[\tilde{g}] R^{\mu\nu\alpha\beta}[\tilde{g}] f d\text{vol}_{(M,\tilde{g})} \quad \tilde{g} = g + h.$$





Conclusions

BV formalism

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Preliminaries

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- We gave a geometrical interpretation of the BV formalism.



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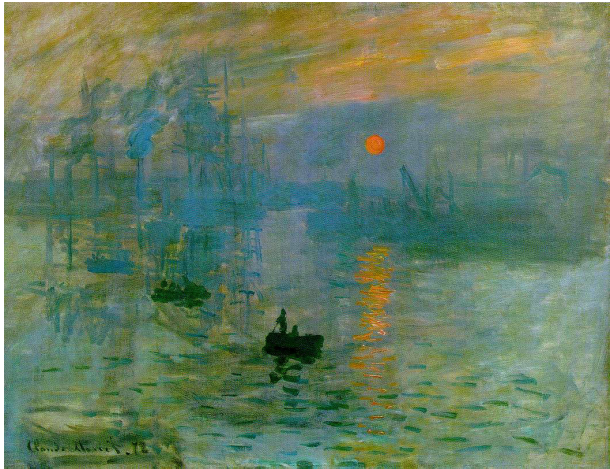


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- In general relativity the basic physical objects are fields (natural transformations), since they are defined not on a fixed background but rather on a class of spacetimes in a coherent way.
- The BV differential can be defined on the algebra of fields Fld and gives a homological interpretation to the notion of *gauge invariant physical quantities* in general relativity.





Thank you for your attention

